# Phil's Orderly Physics Curriculum Important Concepts List (POPCICL) - Interactive Edition 

[Warning : This list is not intended to be comprehensive, but rather to highlight a few key concepts]

## Units

The fundamental units of measurement include : $\qquad$ , $\qquad$ , $\qquad$ , \& electric $\qquad$
Derived units are created from fundamental units by $\qquad$ or $\qquad$ (math operations)
You \{can/cannot\} add, subtract, or equate physical quantities with different units.

## Vectors

Vectors are described by two properties : $\qquad$ and $\qquad$ .

You can change a vector quantity by changing either $\qquad$ or $\qquad$ , or both.

You can describe a vector as a single magnitude and direction, or as $\qquad$ along mutually $\qquad$ axes.
Orthogonal vectors (or vector components) are $\qquad$ .
Independent variables $\{$ do / do not $\}$ directly affect one another.
Vector addition is done graphically by placing the $\qquad$ of one vector at the $\qquad$ of another without $\qquad$ either.
Vector subtraction is done graphically by $\qquad$ the $\{$ first/second $\}$ vector and performing vector addition.
Vector addition is done algebraically by adding the individual $\qquad$ .
A vector dot product between two vectors gives you a \{scalar/vector\} that represents the component of one of the vectors along the direction of the other vector.

## Motion (Kinematics)

Displacement is a \{scalar/vector\} quantity; distance is a \{scalar/vector\} quantity.
If you walk in a complete circle, your $\qquad$ is zero, but your $\qquad$ is non-zero (and equal the circumference of the circle you just walked)
Velocity is the rate of change of $\qquad$ with $\qquad$ ; it tells you how quickly your $\qquad$ is changing.
Velocity is a $\{$ scalar/vector $\}$ quantity; speed is a $\{$ scalar/vector $\}$ quantity.
If run completely around the block, your $\qquad$ is zero because your $\qquad$ is zero; but your $\qquad$ is a non-zero, positive, $\{$ scalar/vector $\}$ quantity.
Acceleration is the rate of change of $\qquad$ with $\qquad$ ; it tells you how quickly your $\qquad$ is changing.
The acceleration due to gravity near the surface of the Earth is equal to $\qquad$
$\qquad$ ; but if if the $y$-axis is directed upwards, then the acceleration due to gravity is given by $a_{y}=$ $\qquad$ .
Quantities of motion (including $\qquad$ , and ) along one orthogonal axis $\{$ do / do not $\}$ affect the quantities of motion along any other orthogonal axis.
Projectile Motion describes the motion of a object that is in motion and subject only to $\qquad$ .
An object in projectile motion (in which we neglect $\qquad$ ), will follow a $\qquad$ trajectory.

## Forces

Without a $\qquad$ applied, objects continue to move with their current velocity, which could be zero. (Newton's First Law)
An object with no net force on it is said to be in $\qquad$ .
The net force on an object is the $\qquad$ of all the forces acting on it.
A net force on an object acts to $\qquad$ it (Newton's Second Law) Doubling the net force on an object will $\qquad$ the resulting acceleration. For the same applied net force, doubling the mass of the object will $\qquad$ the acceleration.
For every force applied by object A onto object B, there is an $\qquad$ and $\qquad$ force applied by
$\qquad$ onto $\qquad$ (Newton's Third Law)
The force of gravity acts as a force of $\qquad$ between the $\qquad$ of any two masses.
Near the surface of the earth, the force of gravity is (nearly) $\qquad$ and always points $\qquad$ .

The force of gravity scales $\qquad$ ly with the mass : double the mass, and the force will $\qquad$ .
The acceleration due to gravity is \{dependent / independent\} of mass. If we ignore air resistance, a feather and a bowling ball \{will / will not\} fall at the same rate.
The restoring force of a spring depends $\qquad$ ly on the stiffness (k) of the spring and $\qquad$ ly on how much the spring is compressed (or stretched) from its relaxed length.
An ideal spring is $\qquad$ less and has no internal $\qquad$ (it doesn't $\qquad$ just by stretching or compressing)
The $\qquad$ force is the force provided by a surface (ground, tabletop) to keep a massive object from breaking through it.
The normal force of a surface always acts $\qquad$ to that surface.
The normal force is a " $\qquad$ " force. Up to the breaking point, the surface always provides $\qquad$ _ of a counter force to counteract the perpendicular (to the surface) component of other forces pulling/pressing an object against the surface.
is the force provided by a flexible connector (rope, string, wire) to keep an object from breaking away from it.
Tension is always directed $\qquad$ the direction of the connector (rope/string/wire)
Tension is a " $\qquad$ " force. Up to the breaking point, the connector always provides of a counter force to counteract the component of other forces pulling/pressing the object away from the connector.
An ideal rope/string/wire is $\qquad$ less and does not $\qquad$ or $\qquad$ .
In an ideal rope, the magnitude of the $\qquad$ is the same throughout the rope.
An ideal pulley changes the $\qquad$ of the tension force but does not change its $\qquad$ .
The force of friction always acts \{parallel / perependicular\} to the surface (the interface between the two rubbing objects) and in the direction that $\qquad$ the motion or attempted motion.
Static friction acts to oppose $\qquad$ motion. Kinetic friction acts to opposes $\qquad$ motion. The coefficient of static friction is generally $\{$ greater / less $\}$ than the coefficient of kinetic friction for the same interface.
Static friction is a " $\qquad$ " force. Up to the "slipping point", the surface always provides $\qquad$ counter force to counteract the parallel (to the surface) component of other forces attempting to push/pull an object along the surface. Kinetic friction is a $\qquad$ force between two objects in motions.

## Direct Stress or Solid Pressure

Solid pressure (a.k.a. Direct Stress) is the applied component of the force) is applied $\qquad$
per unit $\qquad$ on a material when the force (or a to the surface.
The same force applied across a smaller area will result in a $\qquad$ solid pressure.
When solid pressure exceeds the " $\qquad$ strength" of a material, the material will fracture.

## Energy

energy is always conserved. It cannot be created or destroyed; it can only be $\qquad$

There are many forms of energy. Quantitative accounting of some of these forms of energy is difficult (for the beginning physics student), but $\qquad$ energy is straight-forward to calculate.
The Mechanical Energy of an object/system is the sum of the $\qquad$ Energies and $\qquad$ Energies of that object/system.
Kinetic Energy is the energy of $\qquad$ Kinetic energy scales linearly with $\qquad$ but quadratically with of the moving object. Technically, Kinetic Energy is the energy of [coordinated directional] motion; as opposed to the random motion of molecules that make up heat (thermal energy).
Potential Energy is the energy of $\qquad$ , shape or configuration of multiple objects (as in the case for ) or a complex deformable object (as in the case of a ___ ).
A particle or singular object can only have $\qquad$ energy. $\qquad$ energy requires having two or more interacting objects.
Spring Potential Energy scales linearly with the $\qquad$ , but quadratically with $\qquad$

Gravitational Potential Energy near the surface of the Earth scales linearly with the $\qquad$ of the object and also linearly with the $\qquad$ of the object. is the transfer of energy. It has the same units as energy.
Once we have defined what to consider as being in our system, $\qquad$ work is a result of forces acting between two objects that are both inside the system. $\qquad$ work is a result of a force acting between an object in the system and an object outside the system.
Internal work can be due to [mechanically] conservative forces or [mechanically] non-conservative forces.
Positive work done by conservative internal forces associates with a $\qquad$ change in potential energy.
[ ] Conservative Forces (force of gravity, elastic restoring force, and electric [electrostatic] force ) conserve $\qquad$ energy. [ $\qquad$ ] Conservative forces only act to convert one form of energy to another (PE to KE, or KE to PE)
$\square$ ] Non-conservative forces, convert $\qquad$ energy to $\qquad$ forms of energy energy includes heat, light, chemical energy, and nuclear energy.
The force of $\qquad$ converts mechanical energy into heat. We can calculate the amount of heat generated by calculating the work done by the force of friction over a certain $\qquad$ .
External work can cause a change in the $\qquad$ energy of a system, the $\qquad$ energy of a system, or a change in the $\qquad$ energy of the system (if, for example, there is $\qquad$ between two objects that are both the system)
An increase in internal energy corresponds to a rise in $\qquad$ .
Power is the rate of change of $\qquad$ with $\qquad$ .

## Momentum and Collisions

Linear Momentum is defined as $\qquad$ times $\qquad$ and it is a vector quantity (it has magnitude and direction)
Total Linear Momentum is always conserved for an $\qquad$ system.
A system is an isolated system if there is no transfer of $\qquad$ between objects inside the system and anything outside the system.
is the name given to a change in momentum and has the same units as momentum ( $\mathrm{kg} \mathrm{m} / \mathrm{s}$ )
Impulse is a measure of the $\qquad$ of momentum from one object to another.
(this is similar to how " $\qquad$ " was the name given to a change or transfer of energy"
Impulse is the integral of an applied force, integrated over $\qquad$ .
(this is similar to how "work" was the integral of an applied force, integrated over $\qquad$ )
Newton's second law can be more generally written as : the net force on an object is equal to the change in that object's $\qquad$ divided by the duration of the impact.
Momentum is distinct from $\qquad$ . Two objects can have the same momentum but have different
$\qquad$ . Or two objects can have the same $\qquad$ but have different momenta.
A collision with a high kinetic energy object is more likely to cause $\qquad$ or $\qquad$ of the target while a collision with a high momentum object is more likely to cause $\qquad$ of the target.
A collision is any interaction between two objects in which $\qquad$ are applied over a relative $\qquad$ .
In a $\qquad$ collision, the colliding objects separate after the collision with their shape undeformed..
In a $\qquad$ collision, both total momentum and kinetic energy are conserved.
In a $\qquad$ collision, the colliding objects stick together after the collision.
In a $\qquad$ collision, total momentum is conserved, but kinetic energy is not conserved.
Two colliding object separating, but ending up deformed after a collision, is an example of an [non-perfect] collision.
For an elastic collision between two objects in one dimension, the $\qquad$ between the two objects is the same before and after the collision, but with a sign change to indicate a change in relative direction. (this is called the $\qquad$ )
For 2D or 3D collisions, the momentum along each $\qquad$ is conserved independently.

## Center of Mass

The center of mass of an 1D or 2D object is the location for which the object will be $\qquad$ if supported from underneath at that point.
A 3D object will be balanced if the $\qquad$ is directly above or below the pivot/suspension point.
The center of mass of a system or object is found by taking a $\qquad$ -weighted average of the locations of the particle that make up that system or object.
We may treat an extended object as having all its $\qquad$ concentrated at its $\qquad$ for the purpose of linear (non-rotational) motion and forces.
For an isolated system, the momentum of the center of mass of the system $\qquad$ , regardless of any internal forces or collision that occur within the isolated system.

## Circular Motion

Acceleration can be decomposed (broken up) into a $\qquad$ component that is along the direction of motion (direction of the instantaneous velocity vector at any moment) and a $\qquad$ component that is perpendicular to the direction of motion.
Purely tangential acceleration (along the line of motion) only changes the $\qquad$ ( $\qquad$ of the velocity) of an object but not its $\qquad$
Purely centripetal acceleration (perpendicular to the motion) changes the $\qquad$ of an object, but not its speed.
Tangential and centripetal and forces \{are / are not $\}$ new additional forces on a system; they are a $\qquad$ of the existing forces (pushing, pulling, gravity, normal, tension, spring, etc) - decomposing the existing force vectors into "along the motion" and "perpendicular to the motion" components instead of the typical x- and y -components.

## Rotational Motion

When a force is directed $\qquad$ with an object's $\qquad$ , it will cause linear acceleration of the object (translational motion) but no rotational motion.
If a force is directed off-center compared to the object's center-of-mass, it can cause $\qquad$ of the object.
Rotation is described relative to some $\qquad$ , such as a fixed pivot point like a hinge.
If an object does not have a fixed pivot point, rotation occurs about its $\qquad$ .
Analogous to the four quantities of motion for linear motion (displacement, velocity, acceleration, duration), rotation motion is described by four quantities of rotational motion : $\qquad$ , $\qquad$ ,
$\qquad$ , and $\qquad$ )
Angle ( $\theta$ ) and angular displacement ( $\Delta \theta$ ) is measured in $\qquad$ $\left(1 \quad=57.3^{\circ}, 2 \pi\right.$ $\qquad$ $=360^{\circ}$ )
Angular $\qquad$ $(\quad)$ is measured in radians per second.
Angular $\qquad$ ( ) is measured in radians per second-squared.
The (curved) linear distance traveled by a particle undergoing rotation is called the $\qquad$ (symbol, __) and is given by the product of the angular $\qquad$ ( ) and the $\qquad$ from $\qquad$ (r)

|  | is the rotational analog to mass. It is a |
| :--- | :--- |
| A moving _non-point-particle) object can have both_-weighted total mass of an object. |  |
| Analogous to translational kinetic energy, rotational kinetic energy is proportional to the object's |  |
| and the square of its |  |

## Torque \& Angular Momentum

Torque is the rotational analog to $\qquad$ . Torque is a distance-weighted- $\qquad$ , and like $\qquad$ is a vector quantity.
Torque is the cross product between the $\qquad$ vector and the $\qquad$ vector.
A vector cross product between two vectors gives you a vector that represents the how \{parallel / perpendicular\} the two vectors are to each other. The cross-product's direction is determined by the $\qquad$ .
For an extended object to be in static equilibrium, two conditions for equilibrium must be met. The sum of the must be zero, and the sum of the $\qquad$ must be zero.
For an object in static equilibrium, you are free to choose the $\qquad$ to be at any point. Choosing it at a point of force application reduces the number of terms in the $\qquad$ equation.
Newton's three laws of motion $\{$ do / do not $\}$ apply for rotational motion.
An object that is not rotating will $\qquad$ , and an object rotating with constant rotational velocity will $\qquad$ unless acted upon by an external torque.
The net torque on an object is proportional to the its $\qquad$ and its angular acceleration. Doubling the net torque on an object will__ the resulting angular acceleration. For the same applied net torque, doubling the $\qquad$ will halve the angular acceleration.
For every torque applied by object A onto object B , there is an $\qquad$ and $\qquad$ torque applied by B onto A . is the rotational analog to linear momentum.
The angular momentum for a particle is equal to the cross product between the $\qquad$ vector and the
$\qquad$ vector. It's direction is determined by the $\qquad$ .
The angular momentum for an extended object is the product of the its $\qquad$ and angular $\qquad$ .
Angular momentum $\{$ is/ is not $\}$ always conserved for an $\qquad$ system. If the moment of inertia of an system is doubled, its angular velocity will be $\qquad$
Analogous to the alternative formulation of Newton's second law for linear motion; torque can be defined as the time derivative of the $\qquad$ .

