Phil's Orderly Physics Curriculum Important Concepts List (POPCICL) – Interactive Edition

[Warning : This list is not intended to be comprehensive, but rather to highlight a few key concepts]

Units

The fundamental units of measurement include :	,,,	& electric	_			
Derived units are created from fundamental units by	or	(math operation	ns)			
You <u>{can/cannot}</u> add, subtract, or equate physical quantities with different units.						
Vectors						
Vectors are described by two properties :	and					
You can change a vector quantity by changing either _	or	, or both.				
You can describe a vector as a single magnitude and di	irection, or as	along mutually	axes.			
Orthogonal vectors (or vector components) are	<u> </u> .					
Independent variables {do / do not} directly affect one	another.					
Vector addition is done graphically by placing the	of one vector at the	of another without	either.			
Vector subtraction is done graphically by the	ne <u>{first/second}</u> vector a	and performing vec	tor addition.			
Vector addition is done algebraically by adding the inc	lividual	·				
A vector dot product between two vectors gives you a <u>{scalar/vector}</u> that represents the component of one of the vectors along the direction of the other vector.						
Motion (Kinematics)						
Displacement is a <u>{scalar/vector}</u> quantity; distance is	s a <u>{scalar/vector}</u> quant	ity.				
If you walk in a complete circle, your is z circumference of the circle you just walked)	zero, but your	is non-zero (a	nd equal the			
Velocity is the rate of change of with	; it tells you how qui	ckly your	is changing.			
Velocity is a <u>{scalar/vector}</u> quantity; speed is a <u>{scalar</u>	ar/vector} quantity.					
If run completely around the block, your	is zero because y	/our	is zero; but			
your is a non-zero, positi	ve, <u>{scalar/vector}</u> quan	itty.	· 1 ·			
Acceleration is the rate of change of with _	; it tells you now q	ulckly your	_ is changing.			
The acceleration due to gravity near the surface of the the y-axis is directed upwards, then the acceleration	Earth is equal to on due to gravity is given b	$y a_y = $; but if if			
Quantities of motion (including,, affect the quantities of motion along any other	and) along on orthogonal axis.	e orthogonal axis {	<u>do / do not}</u>			
Projectile Motion describes the motion of a object that is in motion and subject only to						
An object in projectile motion (in which we neglect), will fo	llow a	trajectory.			

Forces

Without a ______ applied, objects continue to move with their current velocity, which could be zero. (Newton's First Law)

An object with no net force on it is said to be in _____.

The net force on an object is the ______ of all the forces acting on it.

A net force on an object acts to ______ it (Newton's Second Law) Doubling the net force on an object will ______ the resulting acceleration. For the same applied net force, doubling the mass of the object will ______ the acceleration.

For every force applied by object A onto object B, there is an _____ and _____ force applied by

_____ onto _____ (Newton's Third Law)

The force of gravity acts as a force of _____ between the _____ of any two masses.

Near the surface of the earth, the force of gravity is (nearly) ______ and always points ______.

The force of gravity scales _____ly with the mass : double the mass, and the force will _____.

- The acceleration due to gravity is <u>{dependent / independent}</u> of mass. If we ignore air resistance, a feather and a bowling ball <u>{will / will not}</u> fall at the same rate.
- The restoring force of a spring depends _____ly on the stiffness (k) of the spring and _____ly on how much the spring is compressed (or stretched) from its relaxed length.

An ideal spring is _____less and has no internal _____ (it doesn't _____just by stretching or compressing)

The ______ force is the force provided by a surface (ground, tabletop) to keep a massive object from breaking through it.

The normal force of a surface always acts ______ to that surface.

The normal force is a "_____" force. Up to the breaking point, the surface always provides ______ of a counter force to counteract the perpendicular (to the surface) component of other forces

pulling/pressing an object against the surface.

is the force provided by a flexible connector (rope, string, wire) to keep an object from breaking away from it.

Tension is always directed ______ the direction of the connector (rope/string/wire)

Tension is a "_____" force. Up to the breaking point, the connector always provides ____

- of a counter force to counteract the component of other forces pulling/pressing the object away from the connector.
- An ideal rope/string/wire is _____less and does not _____ or _____.

In an ideal rope, the magnitude of the _____ is the same throughout the rope.

An ideal pulley changes the ______ of the tension force but does not change its ______.

- The force of friction always acts <u>{parallel / perependicular}</u> to the surface (the interface between the two rubbing objects) and in the direction that ______ the motion or attempted motion.
- Static friction acts to oppose _____ motion. Kinetic friction acts to opposes _____ motion. The coefficient of static friction is generally {greater / less} than the coefficient of kinetic friction for the same interface.

Static friction is a "_____" force. Up to the "slipping point", the surface always provides _____ counter force to counteract the parallel (to the surface) component of other forces attempting to

push/pull an object along the surface. Kinetic friction is a ______ force between two objects in motions.

Direct Stress or Solid Pressure

Solid pressure (a.k.a. Direct Stress) is the applied	_ per unit	on a material when the force (or a
The same force applied across a smaller area will result in		colid program
The same force applied across a smaller area will result in	1 a	sond pressure.
When solid pressure exceeds the "	_ strength" of	a material, the material will fracture.
Fnergy		
energy is always conserved. It cannot be cre	eated or destro	ved: it can only be
	aled of desire	
There are many forms of energy. Quantitative accounting beginning physics student), but en	g of some of the straighter of	nese forms of energy is difficult (for the tte it forward to calculate.
The Mechanical Energy of an object/system is the sum of object/system.	the	Energies and Energies of that
Kinetic Energy is the energy of Kinetic energy of Kinetic energy of the moving object. <i>Technically, Kinetic motion; as opposed to the random motion of mole</i>	rgy scales line <i>netic Energy i</i> cules that mai	arly with but quadratically with s the energy of [coordinated directional] ke up heat (thermal energy).
Potential Energy is the energy of, sha) or a complex deformable object (as in t	pe or configue the case of a _	ation of multiple objects (as in the case for).
A particle or singular object can only have energy interacting objects.	gy	energy requires having two or more
Spring Potential Energy scales linearly with the	, but	quadratically with
Gravitational Potential Energy near the surface of the Ear linearly with the of the object.	th scales linea	rly with theof the object and also
is the transfer of energy. It has the same units	as energy.	
Once we have defined what to consider as being in our sy between two objects that are both inside the system an object in the system and an object outside the s	rstem, m system.	work is a result of forces acting work is a result of a force acting between
Internal work can be due to [mechanically] conservative f	forces or [mec	hanically] non-conservative forces.
Positive work done by conservative internal forces associated	ates with a	change in potential energy.
[] Conservative Forces (force of gravity, ela conserve energy. [] Conserve energy to another (PE to KE, or KE to KE)	stic restoring onservative for to PE)	force, and electric [electrostatic] force) rces only act to convert one form of
[] Non-conservative forces, convert	energy to	forms of energy
energy includes heat, light, chemical en	ergy, and nuc	lear energy.
The force of converts mechanical energy in by calculating the work done by the force of fricti	nto heat. We control on over a cert	an calculate the amount of heat generated ain
External work can cause a change in the energy in the energy of the system (if, for exam the system)	of a system, the system of a system of a system, the system is	he energy of a system, or a change between two objects that are both
An increase in internal energy corresponds to a rise in	·	
Power is the rate of change of with	·	

Momentum and Collisions

Linear Momentum is defined as times and it is a vector quantity (it has magnitude and direction)
Total Linear Momentum is always conserved for an system.
A system is an isolated system if there is no transfer of between objects inside the system and anything outside the system.
is the name given to a change in momentum and has the same units as momentum (kg m/s)
Impulse is a measure of the of momentum from one object to another.
(this is similar to how "" was the name given to a change or transfer of energy"
Impulse is the integral of an applied force, integrated over
(this is similar to how "work" was the integral of an applied force, integrated over)
Newton's second law can be more generally written as : the net force on an object is equal to the change in that object's divided by the duration of the impact.
Momentum is distinct from Two objects can have the same momentum but have different but have different momenta.
A collision with a high kinetic energy object is more likely to cause or of the target while a collision with a high momentum object is more likely to cause of the target.
A collision is any interaction between two objects in which are applied over a relative
In a collision, the colliding objects separate after the collision with their shape undeformed
In a collision, both total momentum and kinetic energy are conserved.
In a collision, the colliding objects stick together after the collision.
In a collision, total momentum is conserved, but kinetic energy is not conserved.
Two colliding object separating, but ending up deformed after a collision, is an example of an [non-perfect] collision.
For an elastic collision between two objects in one dimension, the between the two objects is the same before and after the collision, but with a sign change to indicate a change in relative direction.
(this is called the)
For 2D or 3D collisions, the momentum along each is conserved independently.

Center of Mass

- The center of mass of an 1D or 2D object is the location for which the object will be ______ if supported from underneath at that point.
- A 3D object will be balanced if the ______ is directly above or below the pivot/suspension point.
- The center of mass of a system or object is found by taking a _____-weighted average of the locations of the particle that make up that system or object.
- We may treat an extended object as having all its _____ concentrated at its _____ for the purpose of linear (non-rotational) motion and forces.
- For an isolated system, the momentum of the center of mass of the system ______, regardless of any internal forces or collision that occur within the isolated system.

Circular Motion

- Acceleration can be decomposed (broken up) into a _____ component that is along the direction of motion (direction of the instantaneous velocity vector at any moment) and a _____ component that is perpendicular to the direction of motion.
- Purely tangential acceleration (along the line of motion) only changes the _____ (_____ of the velocity) of an object but not its ______

Purely centripetal acceleration (perpendicular to the motion) changes the ______ of an object, but not its speed.

Tangential and centripetal and forces {are / are not} new additional forces on a system; they are a ______ of the existing forces (pushing, pulling, gravity, normal, tension, spring, etc) – decomposing the existing force vectors into "along the motion" and "perpendicular to the motion" components instead of the typical x- and y- components.

Rotational Motion

When a force is directed (translational mo	with an object's	, it will cause linear acceleration of the object				
If a force is directed off-	center compared to the object's ce	enter-of-mass, it can	cause	of the object.		
Rotation is described relative to some, such as a fixed pivot point like a hinge.						
If an object does not have a fixed pivot point, rotation occurs about its						
Analogous to the four quantities of motion for linear motion (displacement, velocity, acceleration, duration), rotation motion is described by four quantities of rotational motion :,,						
	_, and)					
Angle (θ) and angular dis	splacement ($\Delta \theta$) is measured in _	(1	$= 57.3^{\circ}, 2\pi$	$= 360^{\circ})$		
Angular () is measured in radians per second.						
Angular () is measured in radians per second-squared.						
The (curved) linear distance traveled by a particle undergoing rotation is called the (symbol,) and is given by the product of the angular () and the from (r)						
is	the rotational analog to mass. It	is a	weighted to	tal mass of an object.		
A moving (ne	on-point-particle) object can have	e both	and	kinetic energy.		
Analogous to translationa and the square of	al kinetic energy, rotational kinet	ic energy is proporti	onal to the obj	ect's		

Torque & Angular Momentum Torque is the rotational analog to _____. Torque is a distance-weighted-____, and like _____ is a vector quantity. Torque is the cross product between the vector and the vector. A vector cross product between two vectors gives you a vector that represents the how {parallel / perpendicular} the two vectors are to each other. The cross-product's direction is determined by the ______. For an extended object to be in static equilibrium, two conditions for equilibrium must be met. The sum of the must be zero, and the sum of the must be zero. For an object in static equilibrium, you are free to choose the ______ to be at any point. Choosing it at a point of force application reduces the number of terms in the ______ equation. Newton's three laws of motion $\frac{do / do not}{do not}$ apply for rotational motion. An object that is not rotating will ______, and an object rotating with constant rotational velocity will ______ unless acted upon by an external torque. The net torque on an object is proportional to the its ______ and its angular acceleration. ______ *Doubling the net torque on an object will ______ the resulting angular acceleration.* For the same applied net torque, doubling the ______ will halve the angular acceleration. For every torque applied by object A onto object B, there is an _____ and _____ torque applied by B onto A. is the rotational analog to linear momentum. The angular momentum for a particle is equal to the cross product between the ______ vector and the

The angular momentum for a particle is equal to the cross product between the _______vector and the ______vector. It's direction is determined by the ______.

The angular momentum for an extended object is the product of the its ______ and angular _____.

Angular momentum <u>{is/ is not}</u> always conserved for an ______ system. If the moment of inertia of an ______ system is doubled, its angular velocity will be _____.

Analogous to the alternative formulation of Newton's second law for linear motion; torque can be defined as the time derivative of the _____.